

# Engineering Notes

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## Aeroassisted Flight Experiment Aerodynamic Characteristics at Flight Conditions

K. James Weilmuenster\* and Peter A. Gnoffo\*  
NASA Langley Research Center, Hampton,  
Virginia 23665

### Introduction

AEROASSISTED space transfer vehicles<sup>1</sup> use aerodynamic forces during hypersonic aerobraking maneuvers in the upper layers of planetary atmospheres to circularize high-energy, entry trajectories. In order to better understand the flight environment of such a vehicle, a flight experiment has been proposed by research organizations within NASA and is called the Aeroassisted Flight Experiment (AFE).<sup>2</sup>

The success of the AFE project will depend in part on the proper placement of instrumentation on the vehicle surface and on the ability of the vehicle to fly the maximum science payload weight. Both of these factors are impacted by the accuracy to which the trim angle of attack (stagnation-point location) and the pitching-moment characteristics (sizing of the active control system) of the vehicle can be predicted. The initial aerodynamic data base was established using wind-tunnel data where appropriate and computational fluid dynamics (CFD) analysis where the influence of real-gas effects precluded the use of information obtained in ground-based facilities. The initial CFD computations were made using an inviscid code and an equilibrium air-chemistry package and included only the forebody portion of the vehicle.

More recently, a viscous, thermochemical nonequilibrium flow analysis about the complete vehicle, including the wake, has been applied to update the vehicle aerodynamic data base. These two data sets are presented and discussed below.

### Geometry

The AFE vehicle shape is shown in a symmetry plane view in Fig. 1. The vehicle is constructed using a 60-deg elliptic cone of ellipticity 2.0 that has been raked off at a 73-deg angle. The nose is an ellipsoid that is tangent to the cone at all intersection points. At the aft end of the cone, a circular arc, which is tangent to the cone in any meridional plane, is appended to the body. This configuration has been defined mathematically in Ref. 3. In addition, a hexagonal shroud has been appended to the base to provide protection for the science payload.

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\*Senior Research Engineer, Aerothermodynamics Branch, Space Systems Division. Senior Member AIAA.

## Computational Codes

### High Alpha Inviscid Solution

The inviscid equilibrium air-chemistry computations were made using the High Alpha Inviscid Solution<sup>4</sup> (HALIS) code and employing the equilibrium air curve fits of Tannehill et al.<sup>5</sup> Briefly, the HALIS code generates time-asymptotic solutions of the three-dimensional Euler equations utilizing an unsplit MacCormack differencing scheme. The solution space is the volume between the bow shock wave, which is treated as a time-dependent boundary, and the body surface. This leads to a coordinate system defined by the position of the bow shock and body as well as the spatial derivatives along these surfaces.

### Langley Aerothermodynamic Upwind Relaxation Algorithm

Program LAURA<sup>6</sup> (Langley Aerothermodynamic Upwind Relaxation Algorithm) is an upwind-biased, point-implicit relaxation algorithm for obtaining the numerical solution for the governing equations for three-dimensional, viscous, hypersonic flows in chemical and thermal nonequilibrium. The algorithm is derived using a finite-volume formulation in which the inviscid components of flux across cell walls are described with Roe's averaging and Harten's entropy fix with second-order corrections based on Yee's Symmetric Total Variation Diminishing scheme. Because of the point-implicit relaxation strategy, the algorithm remains stable at large Courant numbers without the necessity of solving large, block tridiagonal systems.

### Data Points

Initially, for the purposes of consistency, three points along the nominal AFE trajectory were designed as the points at which all CFD computations would be made. They consisted of a point on the entry portion of the trajectory, a point at the maximum penetration of the atmosphere, and a point on the exit portion of the trajectory. Because of the substantial changes to the nominal trajectory, the addition of a fourth CFD

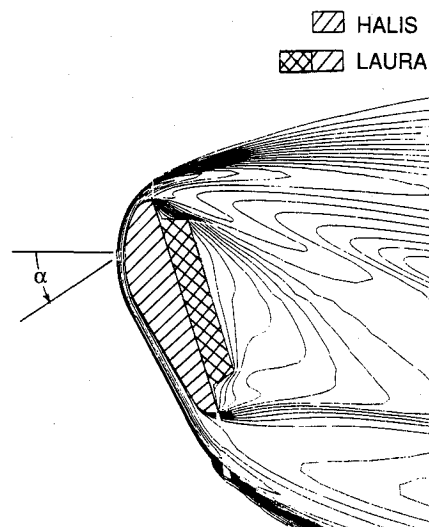


Fig. 1 AFE symmetry plane geometry and vibrational temperature contours ( $\alpha = -5$  deg).

point that corresponds to the point of peak heating on the trajectory for a heavier vehicle was included. The freestream conditions for each of the CFD points are given in Table 1.

### Results and Discussion

In Ref. 7, extensive comparisons were made between aerodynamic coefficients derived from HALIS computations and those measured in ground-based facilities. These included data taken in the 31-in. Mach 10 facility at Langley Research Center where the flow could be modeled as a perfect gas and in

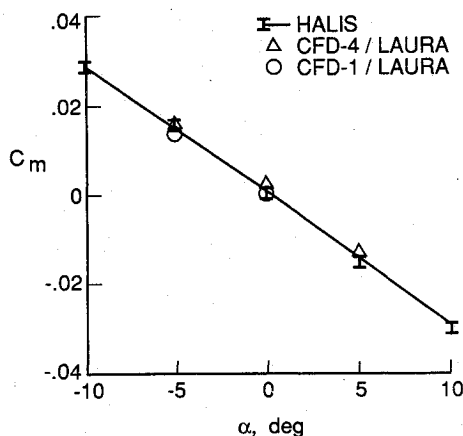


Fig. 2 Comparison of HALIS (forebody) and LAURA (full configuration) AFE pitching-moment characteristics.

Table 1 CFD<sup>a</sup> point freestream conditions

CFD <sup>a</sup> point	$V_{\infty}$ , km/s	$P_{\infty}$ , kg/m <sup>3</sup>	$T_{\infty}$ , K	$h$ , km	$M_{\infty}$
1	9.863	$5.682 \times 10^{-6}$	189.0	87.3	35.70
2	8.914	$2.787 \times 10^{-5}$	197.0	77.9	31.67
3	7.711	$6.080 \times 10^{-6}$	190.3	86.9	27.88
4	9.326	$4.293 \times 10^{-5}$	200.0	75.2	32.88

<sup>a</sup>Computational fluid dynamics.

Table 2 Aeroassisted Flight Experiment aerodynamic coefficients

CFD <sup>a</sup> point	$\alpha$ , deg	$C_N$	$C_A$	$C_m$	Comments
1	0	0.3783	1.349	0.00112	HALIS—inviscid
1	0	0.3840	1.350	0.00125	LAURA—forebody, pressure only
1	0	0.3680	1.382	-0.00078	LAURA—forebody only, pressure + viscous
1	0	0.3650	1.374	0.00100	LAURA—fullbody, pressure + viscous
1	-5	0.3060	1.298	0.01236	LAURA—fullbody, pressure + viscous
2	0	0.3807	1.355	0.00041	HALIS—inviscid
2	0	0.3830	1.340	0.00035	LAURA—forebody only, pressure only
2	0	0.3752	1.342	0.00205	LAURA—fullbody, pressure + viscous
4	0	0.3760	1.334	0.00208	LAURA—fullbody, pressure + viscous
4	-5	0.3213	1.254	0.01517	LAURA—fullbody, pressure + viscous
4	-5	0.3280	1.250	0.01460	LAURA—forebody only, pressure only
4	-5	0.3225	1.258	0.01467	LAURA—forebody only, pressure + viscous
4	-5	0.0012	-0.003	0.00050	LAURA—afterbody only, pressure + viscous
4	5	0.4256	1.402	0.01318	LAURA—fullbody, pressure + viscous

<sup>a</sup>Computational fluid dynamics.

the Langley CF<sub>4</sub> facility where the flow had to be modeled as a real gas. For those comparisons, both the wind-tunnel and computational models were for the forebody portion of the vehicle as shown in Fig. 1 by the shaded area. These comparisons showed that the HALIS code did an excellent job of predicting the vehicle aerodynamics for either a perfect or real gas flow model. Also in Ref. 7, equilibrium air solutions at the various CFD points were made and the resultant aerodynamics compared with the available computational and experimentally derived data base. This comparison indicated that real-gas chemistry has a significant impact on the aerodynamics of the vehicle. In addition Gnoffo and McCandless,<sup>8</sup> using the AFE forebody configuration, predicted the HALIS-generated aerodynamics for a Mach 10, perfect gas flow.

Yet to be determined were the effects of viscosity, base flow, and thermochemical nonequilibrium flow on the vehicle aerodynamics. All of these phenomena are modeled by the current version of the LAURA code, which used the complete configuration shown in Fig. 1 in the computations. The aerodynamic coefficients derived using the HALIS and LAURA codes are compiled in Table 2 for three of the four CFD points. The viscous and thermochemical nonequilibrium chemistry effects on the aerodynamics should be most prominent at CFD point 1, which corresponds to the highest altitude and Mach number conditions being addressed. In Table 2, the first four lines compare the HALIS inviscid aerodynamics at CFD point 1 with those derived from LAURA solutions. When comparing lines 1 and 2, where only pressure is considered over the forebody, HALIS and LAURA aerodynamics are essentially the same. However, inclusion of the viscous forces (line 3, Table 2) has only a small effect as expected for blunt-body flow. Addition of forces on the base of the vehicle (line 4, Table 2) effectively leaves the aerodynamics of the vehicle unchanged. A comparison of the aerodynamics for the CFD point 2 (lines 6–8, Table 2), which is 10 km deeper in the atmosphere than CFD point 1, shows virtually no difference between the HALIS and LAURA results. Also, LAURA results at CFD point 4 (line 9, Table 2), which is at an even lower altitude, are the same as those at CFD point 2.

In Fig. 1, the vibrational temperature contours serve to illustrate the structure of the external flow about the vehicle. For this -5-deg angle of attack, CFD point 4, part of the free shear layer in the upper symmetry plane impinges on the science payload shroud. A decomposition of the LAURA-derived vehicle aerodynamics is given for those conditions in Table 2, lines 10–13. The contribution of forces acting on the base of the vehicle (Table 2, line 13) are seen to be negligible.

These results indicate that the effects of viscosity, thermochemical nonequilibrium chemistry, and base flow on the vehicle aerodynamics are small with any significant changes being limited to flight at the highest altitude. A composite of the pitch and trim characteristics of the vehicle derived from the HALIS and LAURA computations is shown in Fig. 2. The solid line indicates an average pitching moment  $C_m$  derived from the HALIS results while the bars indicate the spread of  $C_m$  over the first three CFD points at each angle of attack. Also shown are values of  $C_m$  derived from LAURA solutions at CFD points 1 and 4. As this figure indicates, across the altitude and Mach number range covered by this study, there is little change in the trim angle of attack and slope of the pitch curve; and the addition of viscous, thermochemical nonequilibrium and base flow effects have had little effect on the vehicle aerodynamics derived from a forebody-only, inviscid, equilibrium chemistry analysis.

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Clark H. Lewis  
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